



U.S. Department of Transportation
Federal Motor Carrier Safety Administration

Automated Commercial Motor Vehicles: State of the Industry and Potential Safety Impacts

2016 Transportation Research Board 95th Annual Meeting
Federal Motor Carrier Safety Administration
Analysis, Research, and Technology Forum
January 11, 2016



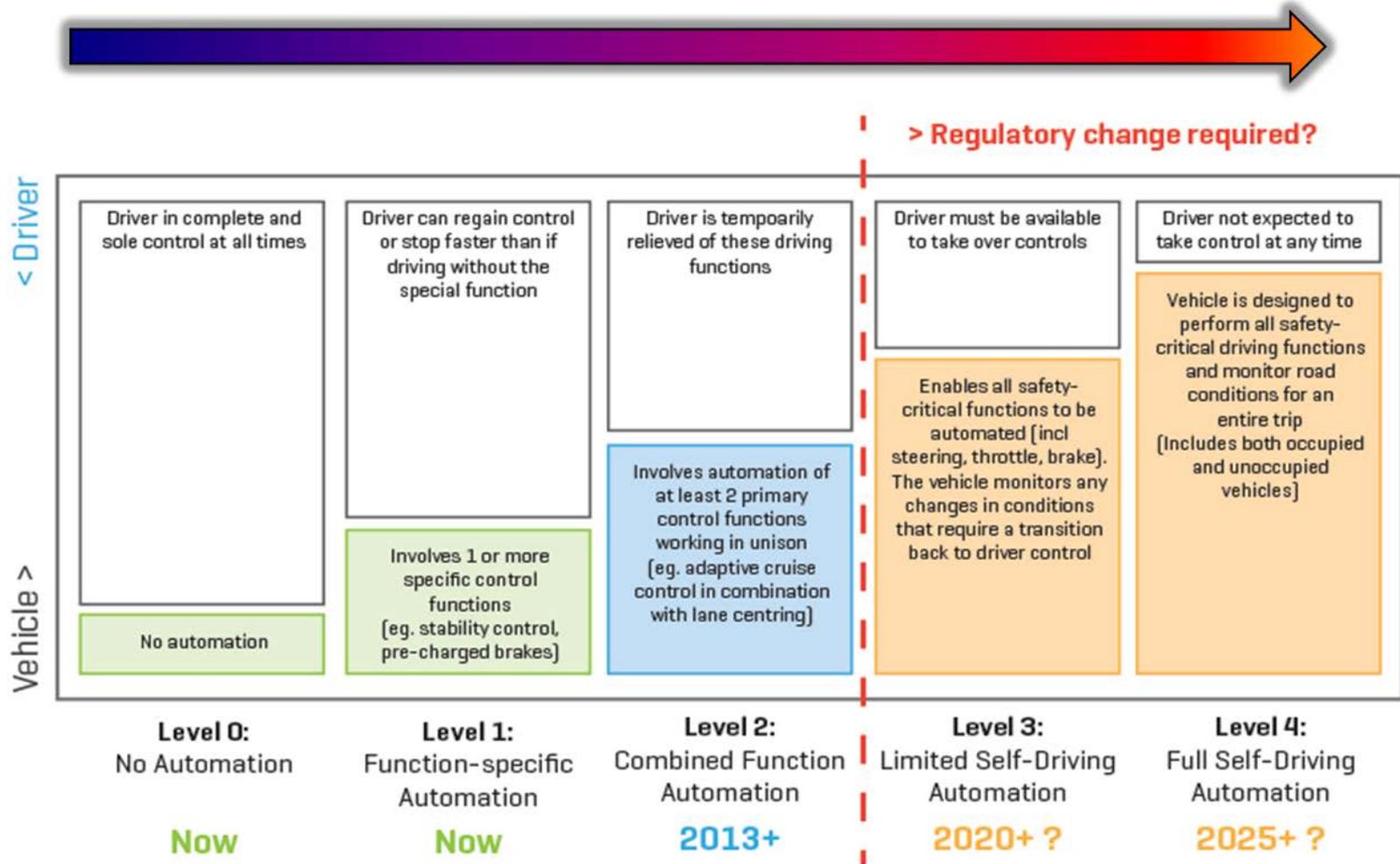
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Office of Research and Information Technology



NHTSA Automation Levels



Source: NHTSA (Modified)

Commercial Vehicle Automation Today: Level 2

- Automatic emergency braking (AEB) now required on heavy trucks in Europe.
- “Optioned In” today, along with:
 - Forward collision warning (FCW).
 - Lane departure warning (LDW).
 - Smart Cruise.



Advanced Automation: Near-Term Implementation—Level 3

- “Low-hanging fruit”
- Constrained environments:
 - Port queues.
 - Distribution warehouses.
 - Mine hauling.



Platooning

- Driver-operated first vehicle.
- Following under lateral and longitudinal control.
- Under ideal conditions, platooning trucks can travel as close as 36 feet from each other.



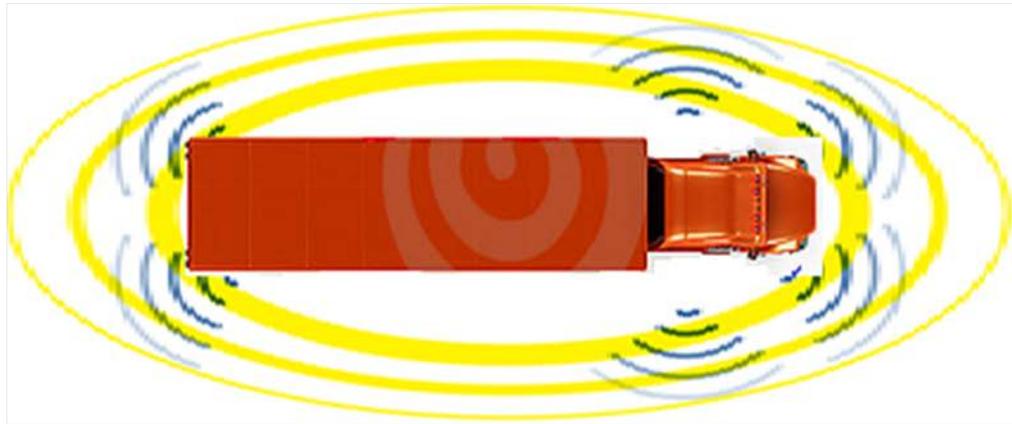
Connected Vehicles

- Vehicle-to-vehicle (V2V)
- Vehicle-to-infrastructure (V2I)



Connected/Automated Vehicle

- Combining V2V, V2I with AV systems.



Connected Automated Vehicle

Leverages autonomous and connected vehicle capabilities

Technical and Policy Challenges

- Public expectations.
- Human factors.
- Cybersecurity.
- Testing and certification complexity.
- Harmonizing State and local regulations.
- National Highway Traffic Safety Administration (NHTSA) mandates?
- Federal Motor Carrier Safety Regulations (FMCSRs).
- Inspections.



Proposed FMCSA Projects

- Commercial Motor Vehicle (CMV) Automated Vehicle Research:
 - Develop a research roadmap to identify the impact to the FMCSRs.
- Low-Speed Automated Truck Queue at Ports and Warehouses:
 - Research of studies.
 - Feasibility study.

Active Federal Highway Administration Projects

- Partial Automation for Truck Platooning:
 - Prime Contractor: California Department of Transportation.
 - Partners: Partners for Advanced Transit and Highways (PATH) (main technical partner, lead); Volvo Technology America; Cambridge Systematics; LA Metro; Gateway Cities; Peloton.
- Heavy Truck Cooperative Adaptive Cruise Control (CACCC)—Evaluation, Testing, and Stakeholder Engagement for Near-Term Deployment:
 - Prime Contractor: Auburn University.
 - Partners: Peterbilt; Meritor Wabco; Peloton; American Transportation Research Institute (ATRI).

FMCSA Joint Projects

- Intelligent Transportation Systems (ITS) Joint Programs Office (JPO) Analysis of Automated Vehicles on FMCSA Enforcement.
- Proposed analysis* in the following areas:
 - Commercial driver's license (CDL) licensing.
 - Safety Measurement System (SMS) algorithm.
 - Hours of service.
 - Investigation/inspection criteria.
 - Advanced inspection tools and techniques.
 - Skill sets for roadside inspectors.

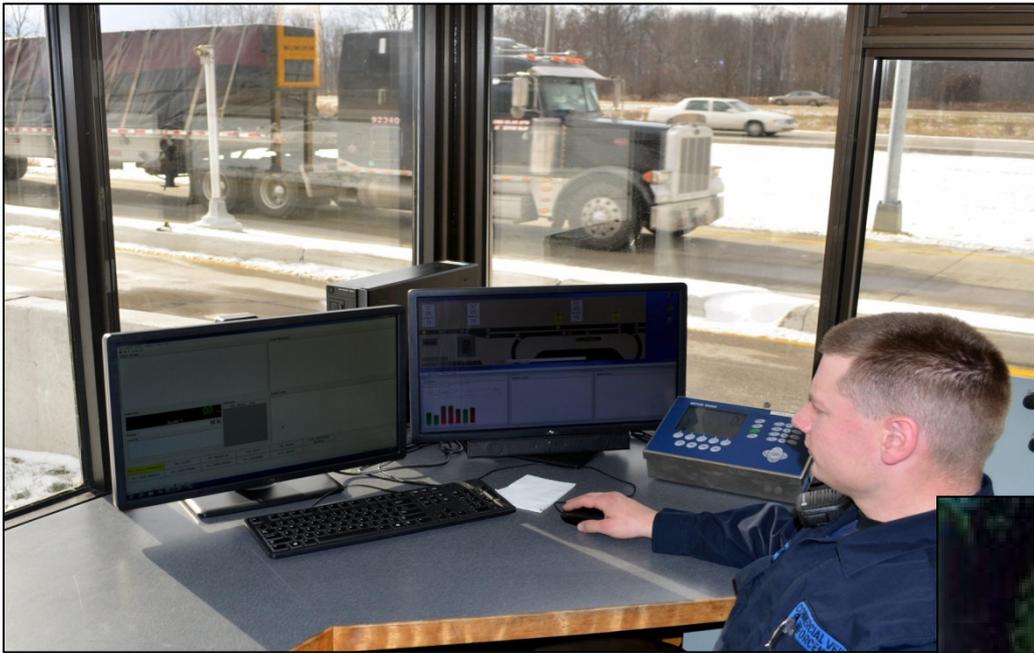
**Proposed within the ITS JPO Automated Vehicle Policy Research Plan.*

How Do We Inspect Advanced Technology?



VISUAL INSPECTION?

How Do We Inspect Advanced Technology?



WIRELESS INSPECTION?



Example of Proposed Project: Antilock Braking System (ABS) Test Tool

- Mandate of electronic stability control (ESC).
- FMCSRs revision.
- Inspection criteria.
- Roadside analysis of the system(s).
- A tool for use by the inspector to quickly and accurately check the “health” of the ABS.
- What about even more advanced technologies if they become ubiquitous?
 - Smart Cruise, Lane Keeping Assist, Automatic backing, etc.



Roadside Inspection?



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Credits

- Special thanks to the following organizations for borrowed content:
 - California PATH
 - Federal Highway Administration
 - NHTSA
 - Peloton
 - North American Council for Freight Efficiency